## SYSMAC CP1H

Multi-functionality Condensed into an All-in-one Package

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Expanded Range of Applications with Built-in Pulse Outputs for 4 Axes,
Analog I/O, and Serial Communications, and with a USB Port as a Standard Feature.


Pulse Output Function
Four Axes are Standard.
Advanced Power for High-precision Positioning Control.
Electrolytic Capacitor Assembly by Electronic Component Manufacturing Equipment
Sheet Feeding for Vertical Pillow Packer


A Full Range of Functions
■Origin Search Function (ORG Instruction) Origin searches are possible with a single ORG instruction.
$\square$ Positioning with Trapezoidal Acceleration and Deceleration (PLS2 Instruction)


CP1H-Y CPU Units offer built-in 1-MHz line-driver I/O. - Line-driver outputs: Two each for CW and CCW. - Line-driver inputs: Two each for phases A, B, and Z. CP1H-Y CPU Units also have 20 normal I/O points (12 inputs and 8 outputs), and can provide $100-\mathrm{kHz}$ high-speed counter inputs for two axes and $30-\mathrm{kHz}$ pulse outputs for two axes.

High-speed Counter Function
Differential Phases for Four Axes Are Standardy"피 Easily Handles Multi-axis Control with a Single Unit.

Main-axis Control for Equipment Such as Textile Machinery or Spinning Machinery

Four-axis Counter Function (Single-phase or Differential Phases) CP1H-Y CPU Units: Two axes, single-phase at 1 MHz or differential phases at 500 kHz plus two axes, single-phase at 100 kHz or differential phases at 50 kHz
CP1H-X $\square$ CPU Units: Four axes, single-phase at 100 kHz or differential phases at 50 kHz
Multi-axis counter inputs enable calculations for inverter positioning, spindle speed control in textile manufacturing, and much more.


Up to Eighit Interupt Inputs Con Be Used

Eight interrupt inputs are built in. Quick-response inputs for pulse widths of $50 \mu \mathrm{~s}$. The interrupt inputs can also be used as singlephase counters. (Response frequency: 5 kHz total for 8 inputs)


The 8 normal inputs ( 6 for Y CPU Units) can be selected in the PLC Setup as interrupt, quick-response, or counter inputs.

# Analog I/O 

Four Input Words and Two Output Words for XA CPU Units. Analog Control and Monitoring with Only a Single CPU Unit

Sismart

## Serial Communications

| A Standard USB Port and Two Serial Ports Enable Connections |
| :--- |
| and Communications with a Wide Range of Components. |

Surface Inspections Using Inspection Devices
Mechanisms to Prevent Careless Mistakes in Cell Production (Such as Forgetting to Tighten Screws)
Oil Pressure Control in Forming Machines
Up to two Option Boards can be mounted for RS-232C or RS-422A/485 communications. A peripheral USB port has been added to connect to a personal computer for a total of three communications ports, making it easy to simultaneously connect to a a Pr, various components (such as inverters, Temperat




Connecting Inverter Speed Control Is Made Simple Using the Modbus-RTU Easy Master
Using the Modbus-RTU Easy Master. When the address, function, and data for a slave device are preset in a fixed memory area (DM Area), a message can be sent or received simply by turning ON in the PLC.



When multiple boilers are being controlled, up to 10 words/Unit of data for settings and monitoring can be (or CJ1M) CPU Units PLC Links can be used with eith serial port 1 or serial port 2.
 CP1H. Each is treated as one slave node.

## A Programming Environment That Shortens Design Time for the Ever-increasing Size and Complexity of Programs.



## A Wealth of Instructions

$\rightarrow$ PID Instruction with Autotuning
PID constants can be automatically tuned for the PID instruction. The limit cycle method is used for tuning, allowing tuning to be completed quickly.

- Floating-point Decimal Instructions,

Trigonometric Instructions, and More. pproximately 400 instructions for ladder programming.

The Structured Text (ST) Language Makes
Arithmetic Operations Even Easier.
In addition to ladder programming, function block logic can be written in ST language, which conforms to IEC 61131-3. Arithmetic processing is also possible with ST, including processing of absolute values, square roots, logarithms, and rigonowe is difficult to write in ladder Processing that is difficult to write in ladder programming becomes easy using structured text.


## Structured Text Commands (Keywords) TRUE, FALSE. <br> IF, THEN, ELSE, ELSIF, END_IF <br> DO, WHILLE, END_WHILE. REPEAT UNTILEND REPEAT. <br> REPEAT, UNTLL, ENDRREPEA FOR, TO, BY, DO, END FOR. CAAE, OF, EXIT, RETUND.CASE.

Operators
Addition ( $($ ), Subtraction ( $(-)$, Multiplication (*), Division ()
Parenthesis ( (brackets) Alray Parenthesis (brackets), Array Indexing (square brackets [ 1 )
Assignment Operator $(:=1$, Less Than Comparison Operator ( $)$, Less Than or Equal To Comparison Operator ( $<=$ ), Greater Than Comparison Operator (>) Greater Than or Equal To Comparison Operator ( $>=$ ), Equals Comparison Operator ( $($ ).
Is Not Equal To Comparison Operator ( $\ll$ )
Is Not Equal To Comparison Operator ( (<>),
Bitwise AND (AND or \&), Bitwise OR (OR), Exclusive OR (XOR), Bitwise AND (AND or \&), Bitwise
NOT (NOT), Exponentiation (**)
Numerical Functions and Arithmetic Functions
ABS, SORT, SORT, LN, LOG, EXP, SIN
ABS,
ATAN, EXPT ATAN, EXPT

Communications Programs Are Provided by the Function Block Library.

The OMRON Function Block (FB) Library provides function blocks for setting SPs, reading PVs, and reading and writing RUN/STOP status and other Temperature Controller parameters. The programmer simply pastes function blocks from the FB Library into the ladder program. The desired functions can be utilized simply by inputting the Temperature Controller unit number and address. The ladder programs used for various
communications can be created from the FB Library, thereby greatly reducing the number of working hours required for program development and debugging

-Security
Eight-character Password Protection


## Advanced Settings Can Be Made with No Need for a Manual, Not Only for the PLC but Even for Special I/O Unit and CPU Bus Unit Parameters and FA Networks.

Easy-to-use Programming Software.
Programming with Function Blocks (Ladder Diagrams/ST Language) Is Also Standard.

## CX-Programmer Nef. 6.1 ortigheer



Shortcut keys can be easily checked using the ladder key guide. Programming is simplified by key inputs, such as the (C) Key for an NC input (contact), the ( Key for an OUT instruction, and the (1) Key for special instructions.
Key inputs are as easy as this: (C) Key, address, (D) Key, comment, (D) Key. The CX-Programmer automatically goes into character input mode when it is time to enter a comment. Special instructions can be input as follows:


Simple key inputs are also available to connect lines.
(C) $+\oplus \oplus \oplus($

Comments can be added for timer and counter instructions through timer and counter input bits.
(1) Consecutive Address Searches

Pressing the (N) Key (Next) jumps to the next input or output bit with the same address.
Pressing the (B)Key (Back) jumps back to the previous input or
output bit with the same address.
(2) Trace Searches

Pressing the Space Bar with the cursor at an input bit jumps to the output bit with the same address. Pressing the Space Bar with the cursor at an output bit jumps to the input bit with the same addres. (3) Cross-reference Popups

Cross-reference information can be displayed for the input or output bit at the cursor to show where the address of the input or output bit is used in the program. Jocation in the program.
lon

■Handle Function Blocks (FB) and Structured Text (ST) Language with Only the CX-Programmer.
Programs using function blocks and ST anguage can be created by reading
function blocks into ordinary ladder programs.

Integrating OMRON PLCs and Component Peripheral Devices.

| FA Integrated Tool Package <br> CX-One <br> Configuration | (1) Network Sofiware | CX-Integrator (Ver. 1.10) CX-Protocol (Ver. 1.70) CX-FLnet (Ver. 1.00) NEW |
| :---: | :---: | :---: |
|  | 2 PLC Sofiwa | CX-Programmer (Ver. 6.10) CX-Simulator (Ver. 1.60) SwitchBox (Ver. 1.70) |
| The CX-One is an FA Integrated Tool Package for connecting, setting, and programming OMRON components including PLCs. CP1H programming and settings can be done with just the CX-Programmer alone, but CX-One is packaged with tools for setting and programming NS-series PTs, Temperature Controllers, and many other components. Using CX-One together with the CP1H makes programming and setup easy, shortening the total lead time required for starting up machines and equipment. | (3) HMI Sofiware | CX-Designer (Ver. 1.00 ) NEW |
|  | (4) Motion Controller Software | CX-Motion (Ver. 2.20 CX-Motion-NCF (Ver. 1.30) CX-Motion-MCH (Ver. 1.00) NEW CX-Position (Ver. 2.10) CX-Drive (Ver. 1.10) NEW |
|  | © PlC-based Progess Control Sofiware | CX-Process Tool (Ver. 5.00) <br> NS-series Face Plate Auto-Builder (Ver. 2.01) |
|  | (0) Component Sofiware | CX-Thermo (Ver 2.01) |

## OCX-Integrator

Settings and communications for devices such as other
PLCs, NS-series
PTs, and
Temperature
are connected to a PLC can all be executed
together from the
CX-One CX-
Integrator
d to the
PLC.


Improved Functional Connectivity with HMI Design Software and Integration of Component Software

Configured with an NS-series PT

## CX-Designer

The CX-Designer can be started from the CX-
The CX-Designer can be started from the CX-
Integrator's NT Link Window. It can be used to desig screens such as, for example, setting screens for Temperature Controllers. In addition, the Smart Active Parts (SAP) library is provided with the CX-Designer to enable easily creating setting screens for Temperature Components or other components.


## Configured with a Temperature Controlle

## CX-Thermo

The Support Software for Temperature Controllers (CX Thermo) can be started from the CX-Integrator's Serial Communications Window.
The CX-Thermo Software can be started from a device in
the CX-Integrator's serial communications (CompoWay/F) network.


Handy Built-in Functions
Make Maintenance Easier.

Flexibly Adjust the System Configuration to the Application by Adding Up to 7 CPM-series Expansion I/O Units, Expanding Functionality, and Connecting to Networks.

CJ-series Special I/O Units and CPU Bus Units Can Be Connected to Meet Current Needs or to Expand the System in the Future.


## ■ Battery-free Operation

The values in the DM Area ( 32 Kwords) are saved in
CPU Unit's built-in flash memory as initial values, and can be read at startup. Battery-free operation is also possible when saving production data and
DM Area, turning OFF the power, and using then same data again for the next production run.

Note:
-A battery is required for the clock
function and to retain the status of function and to retain the status of
HR Area bits and counter values. -A A batea bitrs is and coundeder values.
feature with the ted CPU Unit. - feature with the CPU Unit.
-The user program (ladder program) is stored in buit--in flash
memory, so no battery is required memory, so no battery is required
to back it up.
An analog adjustment and an external analo setting input connector are provided.

-Analog Adjustment The analog adjustment
has a resolution of 256 . Values are entered in A642 and can be used
in the ladder program in the ladder program
When the value is changed, it is displayed
(0 to FF) for three $(0$ to FF) for three
seconds on the 7 seconds on the
segment display.



A maximum of seven CPM1A Expansion I/O Units can be connected. For details on Unit restrictions, refer to page 16.


Expansion I/O Units can also be wired below by using CP1W-CN811 I/O Connecting Cable.

Input Connalog Setting Input Connector This connector has a resolution of
256 and is used for an analog input set to 0 to 10 V. Each CP1H CPU Unit has one of these connectors built in. (The built-in
analog //O for CP1H-XA CPU Unit is separate.) A device, such as a
potentiometer, can be connected and control from a control panel. The maximum cable enghth is 3
meters. A connecting cable 1 meters. A connecting cable ( 1 m )
is included with the CPU Unit.

## Memory Cassette

Data, such as programs and initial memory values, can be stored on opied to Cassette (optional)

- Copied to other systems. used when installing new versions of application programs.



## Status Displayed on

7-segment Display
The 7 -segment display provides
In addition to displaying error codes for errors detected by the PLC, codes can be displayed on the display from the ladder program. maintenance as display is useful for problems that arise during system operation to be grasped without using any Support Software.


An Complete CPU Unit Lineup Lets You Select the Optimum Unit for Your Applications.

CPM-series Expansion I/O Can Be Used without Alteration for
Easy System Expansion.

| CP1H-XA40D $\square-\square$ (CP1H-XA CPU Units) Built-in Analog I/O | CP1H-X40D <br> (CP1H-X CPU Units) <br> Basic Model | CP1H-Y20D $\square$ - $\qquad$ <br> (CP1H-Y CPU Units) <br> High-speed Positioning <br> (To be released soon.) |
| :---: | :---: | :---: |
| CP1H-XA40DR-A <br> AC power supply, 24 DC inputs, 16 relay outputs, 4 analog inputs, 2 analog outputs <br> CP1H-XA40DT-D <br> DC power supply, 24 DC inputs, 16 transistor (sinking) outputs, 4 analog inputs, 2 analog outputs <br> CP1H-XA40DT1-D <br> DC power supply, 24 DC inputs, 16 transistor (sourcing) outputs, $\qquad$ | CP1H-X40DR-A <br> AC power supply, 24 DC inputs, 16 relay outputs <br> CP1H-X40DT-D <br> DC power supply, 24 DC inputs, 16 transistor (sinking) outputs <br> CP1H-X40DT1-D <br> DC power supply, 24 DC inputs, <br> 16 transistor (sourcing) outputs | CP1H-Y20DT-D <br> DC power supply, 12 DC inputs, 8 transistor (sinking) outputs <br> Two 1-MHz line-driver inputs (phases A, B, and Z ) and two $1-\mathrm{MHz}$ line-driver outputs (CW and CCW) are provided separately. |


|  | CP1H-XA CPU Units | CP1H-X CPU Units | CP1H-Y CPU Unit |
| :---: | :---: | :---: | :---: |
| 1/0 capacity | 24 inputs, 16 outputs |  | 12 inputs, 8 outputs <br> Line-driver inputs: Phases $A, B$, and $Z$ for 2 axes Line-driver outputs: CW and CCW for 2 axes |
| High-speed counter | 100 kHz (single-phase), 50 kHz (differential phases), 4 axes |  | 1 MHz (single-phase), 500 kHz (differential phases) for 2 axes (line-driver input), 100 kHz (single-phase), 50 kHz (differential phases) for 2 axes ( 4 axes total) |
| Pulse output function <br> (Models with Transistor Outputs only) | 100 kHz for 2 axes and 30 kHz for 2 axes (4 axes total) |  | 1 MHz for 2 axes (line-driver output), 30 kHz for 2 axes ( 4 axes total) |
| Serial communications | USB port (peripheral port) and 2 optional serial ports (either RS-232C or RS-422A/485 Option Boards) |  |  |
| Analog I/O | 4 analog inputs and 2 analog outputs | - | - |
| Interrupt inputs <br> Quick-response inputs (50-ms width min.) | 8 inputs |  | 6 inputs |
| User program capacity | 20 ks |  |  |
| DM capacity | 32 kw |  |  |
| Maximum number of CPM1A Expansion I/O Units | 7 (Refer to page 16 for Unit restrictions.) |  |  |
| Maximum number of CJ-series Units | 2 (CJ-series Special I/O Units and CPU Bus Units only. Refer to page 16 for information on Units that can be used.) |  |  |

- Options

- Analog Units


Analog Input Unit
Analog
CPM1A-AD041
-Analog inputs: 4 (resolution: 6,000 )

- I/O Connecting Cable



## - CJ-series Special I/O Units and CPU Bus Units

Two CJ-series Special I/O Units or CPU Bus Units can be connected by using a CJ Unit Adapter. (For details on Units that can be used, refer to page16.)


CP1W-ME05M
Memory Cassette

CP1W-CIF01 CP1W-CIF01
RS-232C Option Board


CP1W-CIF11 RS-422A/485
Option Board

- Temperature Sensor Units



## Maximum Number of Expansion Units That Can Be Connected



A maximum of seven CPM1A Expansion I/O Units can be connected, but the following restrictions apply. 7 Units $\geqq$ Number of group A Units + Number of group B Units x 2

Group A Units Counted in the Seven Connectable Units

| Unit type |  | Model |
| :---: | :---: | :---: |
| Expansion I/O Units | $401 / 0$ points | CPM1A-40EDR |
|  |  | CPM1A-40EDT |
|  |  | CPM1A-40EDT1 |
|  | $201 / 0$ points | CPM1A-20EDR1 |
|  |  | CPM1A-20EDT |
|  |  | CPM1A-20EDT1 |
|  | 8 inputs | CPM1A-8ED |
|  | 8 outputs | CPM1A-8ER |
|  |  | CPM1A-8ET |
|  |  | CPM1A-8ET1 |
| Analog Unit | 2 analog inputs, 1 analog output | CPM1A-MAD01 |
|  |  | CPM1A-MAD11 |
| Temperature Sensor Units | 2 thermocouple inputs | CPM1A-TS001 |
|  | 2 platinum resistance thermometer inputs | CPM1A-TS101 |
| CompoBus/S I/ Link Unit | 8 inputs, 8 outputs | CPM1A-SRT21 |
| DeviceNet I/O Link Unit | 32 inputs, 32 outputs | CPM1A-DRT21 |

## Precautions when Using CP1W-CN811 I/O Connecting Cable

Group B Units that Each Count as Two of the Seven Connectable Units

|  | nit type | Model |
| :---: | :---: | :---: |
| Analog Units | 4 analog inputs | CPM1A-AD041 |
|  | 4 analog outputs | CPM1A-DA041 |
| Temperature Sensor Units | 4 thermocouple inputs | CPM1A-TS002 |
|  | 4 platinum resistance thermometer inputs | CPM1A-TS102 |

- CJ-series Special I/O Units and CPU Bus Units

A maximum of two CJ-series Special I/O Units or CPU Bus Units can be connected by using a CP1W-EXT01 CJ Unit Adapter. The number of Units that can be used with the CP1H is as described below.
Use CP1W-CN811 I/O Connecting Cable when using CPM1A Expansion IO Units at the same tim
as a CJ Unit Adapter. In this situation the number of CPM1A Expansion /OO Units that can be as a CJ Unit Adapter. In this situation the number of CPM $1 A$ Expansion I/O Units that can be
connected is subject to the restrictions described above.

| Unit name | Model | Unit name | Model |
| :---: | :---: | :---: | :---: |
| Analog Input Units | CJ1W-AD081-V1 | $\begin{aligned} & \hline \text { Temperature } \\ & \text { Control Units } \end{aligned}$ | CJ1W-TC001 |
|  | CJ1W-AD041-V1 |  | CJIW-TC002 |
| Analog Output Units | CJIW-DA08V |  | CJ1W-TC003 |
|  | CJIW-DA08C |  | CJIW-TC004 |
|  | CJIW-DA041 |  | CJ1W-TC101 |
|  | CJ1W-DA021 |  | CJ1W-TC102 |
| Analog I/O Unit | CJ1W-MAD42 |  | CJ1W-TC103 |
| Process Input Units | CJ1W-PTS51 |  | CJ1W-TC104 |
|  | CJ1W-PTS52 | CompoBus/S Master Unit | CJ1W-SRM21 |
|  | CJ1W-PTS15 |  |  |
|  | CJ1W-PTS16 |  |  |
|  | CJ1W-PDC15 |  |  |


| Unit name | Model |
| :---: | :---: |
| Serial Communications Units | CJ1W-SCU41-V1 |
|  | CJIW-SCU21-V1 |
| Ethernet Unit | CJ1W-ETN21 |
| DeviceNet Unit | CJ1W-DRM21 |
| Controller Link Unit | CJ1W-CLK21-V1 |



## Specifications

## $\square$ CPU Unit Specifications

|  | Item | AC power supply models：CP1H－पדI－A | DC power supply models：CP1H－पםロ－D |
| :---: | :---: | :---: | :---: |
| Power supply |  | 100 to $240 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$ | 24 VDC |
| Operating voltage range |  | 85 to 264 VAC | 20.4 to 26.4 VDC（ 21.6 to 26.4 VDC with four or more Expansion Units．） |
| Power consumption |  | 100 VA max． | 50 W max． |
| Inrush current |  |  | 30 Amax .20 ms max ． |
| External power supply |  | 300 mA at 24 VDC | None |
| Insulation resistance |  | 20 MW min．（at 500 VDC ）between the external AC terminals and GR terminals | 20 MW min．（at 500 VDC ）between the external DC terminals and GR terminals |
| Dielectric strength |  | $2,300 \mathrm{VAC}$ at $50 / 60 \mathrm{~Hz}$ for 1 min between the external AC and GR terminals，leakage current： 5 mA max． | 1,000 VAC at $50 / 60 \mathrm{~Hz}$ for 1 min between the external DC and GR terminals，leakage current： 5 mA max． |
| Noise immunity |  | Conforming to IEC $61000-4-4.2 \mathrm{kV}$（power supply line） |  |
| Vibration resistance |  | 10 to $57 \mathrm{~Hz}, 0.075-\mathrm{mm}$ amplitude， 57 to 150 Hz ，acceleration： $9.8 \mathrm{~m} / \mathrm{s} 2$ in $\mathrm{X}, \mathrm{Y}$ ，and Z directions for 80 minutes each （Sweep time： 8 minutes $\times 10$ sweeps $=$ total time 80 minutes） |  |
| Shock resistance |  | $147 \mathrm{~m} / \mathrm{s}^{2}$ ，three times each in $X, Y$ ，and $Z$ directions |  |
| Ambient operating temperature |  | 0 to $55^{\circ} \mathrm{C}$ |  |
| Ambient humidity |  | 10\％to 90\％（with no condensation） |  |
| Ambient operating environment |  | No corrosive gas |  |
| Ambient storage temperature |  | -20 to $75^{\circ} \mathrm{C}$（Excluding battery．） |  |
| Power holding time |  | $10 \mathrm{~ms} \mathrm{min}$. | $2 \mathrm{~ms} \mathrm{min}$. |
| Dimensions |  | $150 \times 90 \times 85 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$ |  |
| Weight |  | 740 gmax ． | 590 gmax ． |
|  | Item | XA CPU Units：CP1H－XAロロロ－ロ |  |
| Control method |  | Stored program method |  |
| ／／0 control method |  | Cyclic scan with immediate refreshing |  |
| Program language |  | Ladder diagram |  |
| Function blocks |  | Maximum number of function block definitions： 128 Maximum number of instances： 256 Languages usable in function block definitions：Ladder diagrams，structured text（ST） |  |
| Instruction length |  | 1 to 7 steps per instruction |  |
| Instructions |  | Approx． 400 （function codes： 3 digits） |  |
| Instruction execution time |  | Basic instructions： 0.10 нs min．Special instructions： 0.15 нs min． |  |
| Common processing time |  | 0.7 ms |  |
| Program capacity |  | 20 Ksteps |  |
| Number of tasks |  | 288 （ 32 cyclic tasks and 256 interrupt tasks） <br> Scheduled interrupt tasks： 1 （interrupt task No．2，fixed） <br> Input interrupt tasks： 8 （interrupt task No． 140 to 147，fixed）， 6 for Y CPU Units <br> High－speed counter interrupt tasks： 256 （interrupt task No． 0 to 255） |  |
| Maximum subroutin number |  | 256 |  |
| Maximum jump number |  | 256 |  |
| $\begin{aligned} & 1 / 0 \\ & \text { arase } \\ & \text { s.oes } \\ & \text { noied.) } \end{aligned}$ | Input bits | 1，600 bits（100 words）：ClO 0.00 to ClO 99.15 （The 24 built－in inputs are allocated in ClO 0.00 to ClO 0.11 and ClO 1.00 to ClO 1．11．） |  |
|  | Output bits | 1，600 bits（100 words）：CIO 100.00 to C10 199.15 （The 16 built－i outputs aferser | re allocated in C10 100.00 to C10 10．07 and CIO 010．00 to Clo 101．07．） |
|  | Builtin Analog Inputs | ClO 200 to ClO 203 | － |
|  | Builtin Analog Outputs | C10 210 to ClO 211 | － |
|  | $\begin{array}{\|l\|l\|} \hline \text { Serial PLC Link } \\ \text { Area } \end{array}$ | 1，440 bits 990 words）：C10 3100．00 to ClO 3189.15 （C1O 3100 to ClO |  |
| Work bits |  | 8,192 bits（ 512 words）：W000．00 to W511．15（W0 to W511） 37,504 bits（2，344 words）：CIO 3800.00 to CIO 6143.15 （CIO 3800 to CIO 6143） |  |
| TR Area |  | 16 bits：TR0 to TR15 |  |
| Holding Area |  | 8，192 bits（512 words）：H0．00 to H511．15（H0 to H511） |  |
| AR Area |  | Read－only（Write－prohibited）： 7168 bits（ 448 words）：A0．00 to A447．15（A0 to A447） Read／Write： 8192 bits（ 512 words）：A448．00 to A959．15（A448 to A959） |  |
| Timers |  | 4，096 bits：To to T4095 |  |
| Counters |  | 4，096 bits：C0 to C4095 |  |
| DM Area（See note．） |  | 32 Kwords：Do to D32767 |  |
| Data Register Area |  | 16 registers（16 bits）：DR0 to DR15 |  |
| Index Register Area |  | 6 registers（16 bits）： RO 0 to 1 R15 |  |
| Task Flag Area |  | 32 flags（32 bits）：TK0000 to TK0031 |  |
| Trace Memory |  | 4,000 words（ 500 samples for the trace data maximum of 31 bits and 6 words．） |  |
| Memory Cassette |  | A special Memory Cassette（CP1W－ME05M）can be mounted．Note：Can be used for program backups and auto－booting． |  |
| Clock function |  | Supported．Accuracy（monthly deviation）：-3.5 min to -0.5 min （ambient temperature： $55^{\circ} \mathrm{C}$ ）， <br> -1.5 min to +1.5 min （ambient temperature： $25^{\circ} \mathrm{C}$ ），-3 min to +1 min （ambient temperature： $0^{\circ} \mathrm{C}$ ） |  |
| Communications functions |  | One built－in peripheral port（USB1．1）：For connecting Support Software only．A maximum of two Serial Communications Option Boards can be mounted． |  |
| Memory backup |  | Flash memory：User programs，parameters（such as the PLC Setup），comment data，and the entire DM Area can be saved to flash memory as initial values Battery backup：The Holding Area，DM Area，and counter values（flags，PV）are backed up by a battery． |  |
| Battery service life |  | 5 years at $25^{\circ} \mathrm{C}$ ．（Use the replacement battery within two years of manufacture．） |  |


| Item | XA CPU Units：CP1H－XAロロロ－ם | x CPU Units：CP1H－XロID－प | CY CPU Units：CP1H－Yロपם－ם |
| :---: | :---: | :---: | :---: |
| Built－in input terminals | 40 （24 inputs， 16 outputs） |  | 20 （12 inputs， 8 outputs） <br> Line－driver inputs：Two axes for phases A，B，and Z Line－driver outputs：Two axes for CW and CCW |
| Number of connectible Expansion（I／O）Units | CPM1A Expansion IOO Units： 7 max．；CJ－series Special IOO Units or CPU Bus Units： 2 max． |  |  |
| Max．number of／O points | 320 （40 built in +40 per Expansion（／／）Unit $\times 7$ Units） |  | 300 （20 built in +40 per Expansion（1／0）Unit $\times 7$ Units） |
| Interrupt inputs | 8 inputs（Shared by the external interrupt inputs（counter mode）and the quick－response inputs．） |  | 6 inputs（Shared by the external interrupt inputs （counter mode）and the quick－response inputs．） |
| Interrupt inputs counter mode | 8 inputs（Response frequency： 5 kHz max．for all interrupt inputs）， 16 bits |  | 6 inputs（Response frequency： 5 kHz max． for all interrupt inputs）， 16 bits |
| Quick－response inputs | 8 points（Min．input pulse width： 50 us max．） |  | 6 points（Min．input pulse width： $50 \mu \mathrm{~s}$ max．） |
| Scheduled interrupts |  |  |  |
| High－speed counters | 4 inputs：Differential phases（ 4 x ）， 50 kHz or <br> Single－phase（pulse plus direction，up／down，increment）， 100 kHz Value range： 32 bits，Linear mode or ring mode Interrupts：Target value comparison or range comparison |  | 2 innuts：Differential phases（ $4 \times \mathrm{x}$ ）， 500 kHz or Single－phase， 1 MHz and 2 inputs：Differential phases 4 x ）， 50 kHz or Single－phase（pulse plus direction，up／down，increment）， 100 kHz Value range： 32 bits，Linear mode or ring mode |
| Pulse outputs（models with transistor outputs only） | Trapezoidal or S－curve acceleration and deceleration（Duty ratio： $50 \%$ fixed） 2 outputs， 1 Hz to 100 kHz （CCW／CW or pulse plus direction） 2 outputs， 1 Hz to 30 kHz （CCW／CW or pulse plus direction） PWM outputs ：（Duty ratio： $0.0 \%$ to $100.0 \%$（Unit： $0.1 \%)$ ）2 outputs， 0.1 to $1 \mathrm{kHz}($ Accuracy $\pm 5 \%$ at 1 kHz$)$ |  | Trapezoidal or S－curve acceleration and deceleration （Duty ratio：50\％fixed） <br> 2 outputs， 1 Hz to 1 MHz （CCW／CW or pulse plus direction） 2 outputs， 1 Hz to 30 kHz （CCW／CW or pulse plus direction PWM outputs ：（Duty ratio：0．0\％to $100.0 \%$（Unit： $0.1 \%$ ） 2 outputs， 0.1 to 1 kHz （Accuracy：$\pm 5 \%$ at 1 kHz ） |
| Built－in analog／／0 terminals | 4 analog inputs and 2 analog outputs （Refer to separate detailed specifications．） |  | None |
| Analog control | 1 （Setting range： 0 to 255） |  |  |
| External analog input | 1 input（Resolution： $1 / 256$, Input range： 0 to 10 V ） |  |  |
| $\square$ Serial Communications Specifications |  |  |  |
| Item | Function |  | Interface |
| Peripheral USB port | For connecting Peripheral Device． |  | Conforms to USB 1．1，B－type connector |
| Serial port 1 | Host Link，No－protocol，NT Link（1：N），Serial PLC Link（See note．）， Serial Gateway（CompoWay／F master，Modbus－RTU master）， Modbus－RTU easy master function |  | The CP1W－CIF01 RS－232C Option Board <br> पсомм $\square$ <br> or the CP1W－CIF11 RS－422A／485 Option Board |
| Serial port 2 | Host Link，No－protocol，NT Link（1：N），Serial PLC Link（See note．）， Serial Gateway（CompoWay／F master，Modbus－RTU master）， Modbus－RTU easy master function |  | CP1W－CIF11 RS－422A／485 Option Board <br> used with either port． |

Analog I／O Specifications（CP1H－XA CPU Units Only）

|  | tem | Voltage／／o | Current／／0 |
| :---: | :---: | :---: | :---: |
|  | Number of analog inputs | 4 |  |
|  | Input signal range | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V}, 0$ to 10 V ，or -10 to 10 V | 0 to 20 mA or 4 to 20 mA |
|  | Max．rated input | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |
|  | Exteral inputimpedance | $1 \mathrm{M} \Omega \mathrm{min}$ ． | Approx． $250 \Omega$ |
|  | Resolution | 1／6，000 or 1／12，000（full scale） |  |
|  | Overall accuracy | $25^{\circ} \mathrm{C}: \pm 0.3 \%$ full scale／0 to $55^{\circ} \mathrm{C}: \pm 0.6 \%$ full scale | $25^{\circ} \mathrm{C}: \pm 0.4 \%$ full scale／0 to $55^{\circ} \mathrm{C}$ ：$\pm 0.8 \%$ full scale |
|  | A／D conversion data | Full scale for－ 10 to 10 V：F448（E890）to 0BB8（1770）Hex Full scale for other ranges： 0000 to 1770 （2EEO）Hex |  |
|  | Averaging | Supported（Set for individual inputs in the PLC Setup．） |  |
|  | Open－circuit detection | Supported（Value when disconnected： 8000 Hex ） |  |
|  | Number of outputs | 2 outputs |  |
|  | Output signal range | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V}, 0$ to 10 V ，or -10 to 10 V | 0 to 20 mA or 4 to 20 mA |
|  | Allowable external output load resistance | $1 \mathrm{k} \Omega$ min． | $600 \Omega$ max． |
|  | External output impedance | $0.5 \Omega$ max． | － |
|  | Resolution | 1／6，000 or 1／12，000（full scale） |  |
|  | Overall accuracy | $25^{\circ} \mathrm{C}: \pm 0.4 \%$ full scale／0 to $55^{\circ} \mathrm{C}: \pm 0.8 \%$ full scale |  |
|  | D／A conversion data | Full scale for－10 to 10 V ：F448（E890）to 0BB8（1770）hex Full scale for other ranges： 0000 to 1770 （2EEO）hex |  |
| Conversion time |  | $1 \mathrm{~ms} / \mathrm{point}$ |  |
|  | lation method | Photocoupler isolation between analog 1／0 terminals and | cuits．No isolation between analog／／O signals． |

## I/O Specifications

## Built-in Input Area

## $\square X A$ and $X$ CPU Units

| $\begin{aligned} & \begin{array}{l} \text { LLC } \\ \text { Setup } \end{array} \end{aligned}$ |  | Input operation |  |  | High-speed counter operation | Puse outputo origin search tunction setto be used. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Normal inputs | Interrupt inputs | Quick-response inputs | High-speed counters | Origin search |
| $\begin{aligned} & \hline \mathrm{ClO} \\ & 0 \end{aligned}$ | 00 | Normal input 0 | Interrupt input 0 | Quick-response input 0 |  | Pulse 0 : Origin input signal |
|  | 01 | Normal input 1 | Interrupt input 1 | Quickresponse input 1 | High-speed counter 2 (phase-Zreset) | Pulse 0 : Origin proximity input signal |
|  | 02 | Normal input 2 | Interupt input 2 | Quickresponse input 2 | High-speed counter 1 (phase-Zreset) | Pulse output 1 : Origin input signal |
|  | 03 | Normal input 3 | Interrupt input 3 | Quick-response input 3 | High-speed counter 0 (phase-Zreset) | Pulse output 1 : Origin proximity input signal |
|  | 04 | Normal input 4 |  |  | High-speed counter 2 (phase-A, increment, or count input) |  |
|  | 05 | Normal input 5 |  |  | High-speed counter 2 (phase-B, decrement, or direction input) |  |
|  | 06 | Normal input 6 |  |  | High-speed counter 1 (phase-A, increment, or count input) |  |
|  | 07 | Normal input 7 |  |  | High-speed counter 1 (phase-B, decrement, or direction input) |  |
|  | 08 | Normal input 8 |  |  | High-speed counter 0 (phase-A, increment, or count input) |  |
|  | 09 | Normal input 9 |  |  | High-speed counter 0 (phase-B, decrement, or direction input) |  |
|  | 10 | Normal inut 10 |  |  | High-speed counter 3 (phase-A, increment, or count input) |  |
|  | 11 | Normal output 11 |  |  | High-speed counter 3 (phase-B, decrement, or direction input) |  |
| $\begin{aligned} & \text { cio } \\ & 1 \end{aligned}$ | 00 | Normal inut 12 | Interrup input 4 | Quick-response input 4 | High-speed counter 3 (phase-Zreset) | Pulse output 2 : Origin input signal |
|  | 01 | Normal inut 13 | Interrupt input 5 | Quick-response input 5 |  | Pulse output 2 : Origin proximity inut signal |
|  | 02 | Normal inut 14 | Interupt input 6 | Quick-response input 6 |  | Pulse output 3 : Origin input signal |
|  | 03 | Normal inut 15 | Interrupt input 7 | Quick-response input 7 |  | Pulse output 3 : Origin proximity input signal |
|  | 04 | Normal inut 16 |  |  |  |  |
|  | 05 | Normal inut 17 |  |  |  |  |
|  | 06 | Normal inut 18 |  |  |  |  |
|  | 07 | Normal inut 19 |  |  |  |  |
|  | 08 | Normal inut 20 |  |  |  |  |
|  | 09 | Normal inut 21 |  |  |  |  |
|  | 10 | Normal inut 22 |  |  |  |  |
|  | 11 | Normal inut 23 |  |  |  |  |

$\square$ Y CPU Units

| $\begin{gathered} \text { Input } \\ \text { terme } \\ \text { tormine } \\ \text { block } \end{gathered}$ |  | Input operation setting |  |  | High-speed counter operation setting High-speed counters | Pulse output origin search function set to be used. Origin search |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Normal inputs | Interrupt inputs | Quick-response inputs |  |  |
| $\begin{aligned} & c_{10}^{c} \\ & 0 \end{aligned}$ | 00 | Normal input 0 | Interupt input 0 | Quick-esponse input 0 |  | Pulse 0: Origin input signal |
|  | 01 | Normal input 1 | Interupt input 1 | Quick-esponse input 1 | High-speed counter 2 (phase-/reset) | Pulse 0 : Origin proximity input signal |
|  | 02 | -- | -- | -- | High-speed counter 1 (phase-Z/resel) fived |  |
|  | 03 | -- | -- | -- | High-speed counter 0 (phase-z/reseli) fixed |  |
|  | 04 | Normal input 4 |  |  | High-speed counter 2 (phase-A, increment, or count input) |  |
|  | 05 | Normal input 5 |  |  | High-speed counter 2 (phase-B, decrement, or direction input) |  |
|  | 06 | -- | -- | -- | High-spegd counter 1 (phase A, incerment, or count input fived |  |
|  | 07 | -- | -- | -- | Highspeed counter 1 (phase B, dearement, ordircation inpul) ited |  |
|  | 08 | -- | -- | -- | High spead counter O Pophase A, inceremt, or count input fixed |  |
|  | 09 | -- | -- | -- | Highspeed countero Ophase B, dearement, ordirection inuut ived |  |
|  | 10 | Normal input 10 |  |  | High-speed counter 3 (phase-A, increment, or count input) fixed |  |
|  | 11 | Normal input 11 |  |  | High.speed counter 3 (phase-B, decrement, or direction input) fixed |  |
| $\mathrm{c}_{1}^{\mathrm{co}}$ | 00 | Normal input 12 | Interupt input 4 | Quick-esponse input 4 | High-speed counter 3 (phase-/reset) | Pulse output 1: Origin input signal |
|  | 01 | Normal input 13 | Interupt input 5 | Quick-esponse input 5 |  | Pulse output 2: Origin input signal |
|  | 02 | Normal input 14 | Interupt input 6 | Quick-esponse input 6 |  | Pulse output 3 : Origin input signal |
|  | 03 | Normal input 15 | Interupt input 7 | Quick-esponse input 7 |  | Pulse output $1:$ Orgigin proximity input signal |
|  | 04 | Normal input 16 |  |  |  | Pulse output: 2 Origin proximity input signal |
|  | 05 | Normal input 17 |  |  |  | Pulse output 3 : origin proximity input signal |

These areas are for line.driver inputs, so they are can be used only for high.speed counters 11 MHz ) and not for other purposes, such as ormal inputs.

## Built-in Output Area

| Instructions/ PLC Setup |  | $\begin{gathered} \text { When the } \\ \text { instructions to the } \end{gathered}$ | When a pulse output instruction (SPED, ACC, PLS2, or ORG) is executed |  | When the origin search function is set to be used in the PLC Setup, and an origin | When the PWM instruction is executed |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | executedNormal output | Fixed duty ratio pulse output |  |  | Variable dutr ratio pulse output |
|  |  | cw/ccw | Pulse plus direction | When the origin search function is used | PWM output |
| $\begin{gathered} c_{100}^{100} \end{gathered}$ | 00 |  | Normal output 0 | Pulse output 0 ( CW ) | Pulse output 0 ( pulse) |  |  |
|  | 01 | Normal output 1 | Pulse output 0 ( CWW ) | Pulse output 1 ( (pulse) |  |  |
|  | 02 | Normal output 2 | Pulse output 1 (CW) | Pulse output 0 (direction) |  |  |
|  | 03 | Normal output 3 | Pulse output 1 (CCW) | Pulse output 1 (direction) |  |  |
|  | 04 | Normal output 4 | Pulse output 2 (CW) | Pulse output 2 (pulse) |  |  |
|  | 05 | Normal output 5 | Pulse output 2 (CCW) | Pulse output 2 (direction) |  |  |
|  | 06 | Normal output 6 | Pulse output 3 (CW) | Pulse output 3 (pulse) |  |  |
|  | 07 | Normal output 7 | Pulse output 3 (CCW) | Pulse output 3 (direction) |  |  |
| $\begin{aligned} & \text { cio } \\ & 100 \end{aligned}$ | 00 | Normal output 8 |  |  |  | PWM output 0 |
|  | 01 | Normal output 9 |  |  |  | PWM output 1 |
|  | 02 | Normal output 10 |  |  | Origin search 0 (Error counter reset output) |  |
|  | 03 | Normal output 11 |  |  | Origin search 1 (Error counter reset output) |  |
|  | 04 | Normal output 12 |  |  | Origin search 2 (Error counter reset output) |  |
|  | 05 | Normal output 13 |  |  | Origin search 3 (Error counter reset output) |  |
|  | 06 | Normal output 14 |  |  |  |  |

## - Y CPU Units



CP1H CPU Unit Terminal Block Arrangement

| $\stackrel{\text { - CPiH-X } \square \text { CPU Units }}{\text { with AC power supply }}$ |  |
| :---: | :---: |
| - ${ }^{\text {CPITH-X }}$ CPPU Units with DC power supply |  |
| - CP1H-Y CPU Units |  |

- Built-in Analog IOOTerminal Slock Arrangement for
CP1H-XA CPU Units
$\begin{aligned} & \text { Voltage input } \\ & \text { (default setting) }\end{aligned}$

0000000 000000000

## I/O Specifications

## Input Specifications

| Hem | Specifications |  |  |
| :---: | :---: | :---: | :---: |
| CPIH-AAX CPU Units | C10 0.04 to clio 0.11 |  | C10 1.04 toclo |
| CPIH-Y CPU Units | C10 0.04, C10 0.0.5, 1100.10, c10 0.11 | C10 0.00, Clo 0.01 a and Clo 1.0 to to 10.003 | C10 1.04, 1010.05 |
| Input voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |  |  |
| Applicable sensors | 2 -wire sensors |  |  |
| Input impedance | 3.3 k 2 | 3.0 k | 4.7 k 2 |
| Input current | 7.5 mAtypical | 8.5 mAtppical | 5 mAtypical |
| ON voltage | 17.0 VDCO min. | 17.0 VDC min. | $14.4 \mathrm{vDC} \mathrm{min}$. |
| OFF voltagelucrent | 1 mA max at 5.0 VDC | 1 mA max at 5.0 vDC | 1 mA max at 5.0 VDC |
| ON delay | 2.5 us max. | 50 us max. | 1 ms max . |
| OFF delay | 2.5 us max. | 50 us max. | 1 ms max. |
| Circuit onfiguration | 这 | 速 |  |

- CP1H-XA/X CPU Units

Input bits: CIO 0.04, CIO 0.06, CIO 0.08, CIO 0.10 (Phase A)

- CP1H-Y CPU Units

Input bits: CIO $0.04, \mathrm{CIO} 0.10$ (Phase A) CIO 0.05, CIO 0.11 (Phase B)
Pulse plus direction input mod
ucrement mode


CP1H-XA/X CPU Units
Input bits: CIO 0.00 to $\mathrm{CIO} 0.03, \mathrm{CIO} 1.00$ to CIO 1.03
CP1H-Y CPU Units
Input bits: CIO 0.00, CIO 0.11, CIO 1.00 to CIO 1.03


## ■ Output Specifications

| Item |  |  | Specifications |
| :---: | :---: | :---: | :---: |
| Max. switching capacity |  |  | $2 \mathrm{~A}, 250 \mathrm{VAC}($ cos $\mathrm{s}=1 \mathrm{l}, 2 \mathrm{AA}, 24 \mathrm{VDC} 4 \mathrm{~A}$ (commmon) |
| Min. switching capacity |  |  | $5 \mathrm{VDC}, 10 \mathrm{~mA}$ |
| Service life of relay | Electrical | Resistive load | 100,000 operations (24 VDC) |
|  |  | Inductive load | $48,000$ operations (250 VAC, $\cos \phi=0.4)$ |
|  | Mechanical |  | 20,000,000 operations |
| ON delay |  |  | 15 ms max. |
| OFF delay |  |  | 15 ms max. |
| Circuit configuration |  |  |  |

$$
\begin{aligned}
& \text { Under the worst conditions, the service life of output contacts is } \\
& \text { as show on the left. } \\
& \text { The service life of relays is as shown in the following diagram }
\end{aligned}
$$

$$
\begin{aligned}
& \text { The service elife e } \\
& \text { as a auideline }
\end{aligned}
$$

## $\square$ CPU Units with Transistor Outputs (Sinking/Sourcing)



Note 1 : Fuses cannot be replaced by the





Note:
Do not toply a voltage or connecta load to
an outputerninat exceding the maximum
switching capacity

$\square$ Input Specifications for CPM1A-40EDR/40EDT/40EDT1/20EDR1/20EDT/20EDT1/8ED


## Output Specification

$\xrightarrow[\text { Max. switching capacity }]{\text { Item }}$ Max.s switching capacity $\quad 2 \mathrm{~A}, 250 \mathrm{VAC}$


 | relay | Mechanical | $20,000,000$ operations |
| :--- | :--- | :--- | :--- | :--- |

$\qquad$

Under the worst conditions, the serice lie


OFF Outputs (Sint 15 ms

| Item | Specifications |  |  | Circuit configuration |
| :---: | :---: | :---: | :---: | :---: |
|  | CPM1A-40EDT CPM1A-40EDT1 | CPM1A-20EDT CPM1A-20EDT1 | CPM1A-8ET CPM1A-8ET1 | gouputs. |
| Max. switching capacity <br> (See note 2.) | 4.5 to 30 VDC: <br> 0.3 A/point | $\begin{aligned} & 4 \mathrm{VDC}+10 \% /-5 \% \text { : } \\ & 0.3 \mathrm{~A} \text { Apoint } \end{aligned}$ | - OUTOO/OUTO1: 0.2 A/point at 4.5 to 30 VDC <br> - OUTO2 to OUTO7: 0.3 A point at 4.5 to 30 VDC |  |
|  | 0.9 A/common 3.6 A/common | 0.9 A/common $1.8 \mathrm{~A} /$ common | 0.9 A/common 1.8 A/common |  |
| Leakage current | 0.1 mA max. | 0.1 mA max. | 0.1 mA max. |  |
| Residual voltage | 1.5 V max. | 1.5 V max. | 1.5 V max. |  |
| ON delay | 0.1 ms max. | 0.1 ms max. | 0.1 ms max. |  |
| OFF delay | 1 ms max. at 24 VDC $+10 \% /-5 \%, 5$ to 300 mA | $\begin{aligned} & 1 \mathrm{~ms} \text { max. at } 24 \mathrm{VDC} \\ & +10 \% /-5 \%, 5 \text { to } 300 \mathrm{~mA} \\ & \hline \end{aligned}$ | 1 ms max. at 24 VDC $+10 \% /-5 \%$, 5 to 300 mA |  |
| Fuse (See note 1.$)$ | None | 1/common |  |  |






## Expansion I/O

| $\begin{aligned} & \text { Analog Input Unit } \\ & \text { CPM1A-AD041 } \end{aligned}$ |  |  |  |
| :---: | :---: | :---: | :---: |
| Item |  | CPM1A-AD041 |  |
|  |  | Input voltage | Input current |
| Number of inputs |  | 4 |  |
| Input signal range |  | 0 to $5 \mathrm{~V}, 1$ to 5 V , 0 to 10 V , or -10 to 10 V | 0 to 20 mA or <br> 4 to 20 mA |
| Max. rated input |  | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |
| External input impedance |  | $1 \mathrm{M} \Omega$ min. | Approx. $250 \Omega$ |
| Resolution |  | 6000 |  |
| Overall accuracy | $25^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ of full scale | $\pm 0.4 \%$ of full scale |
|  | 0 to $55^{\circ} \mathrm{C}$ | $\pm 0.6 \%$ of full scale | $\pm 0.8 \%$ of full scale |
| Conversion time |  | $2.0 \mathrm{~ms} / \mathrm{point}$ |  |
| AD conversion data |  | Binary data with resolution of 6,000 <br> Full scale for -10 to 10 V : F448 (E890) to 0BB8 (1770) hex Full scale for other ranges: 0000 to 1770 (2EEO) hex |  |
| Averaging |  | Supported |  |
| Open-circuit detection |  | Supported |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega$ min. (at 250 VDC , between isolated circuits) |  |
| Dielectric strength |  | 500 VAC for 1 min (between isolated circuits) |  |
| Isolation method |  | Photocoupler isolation (between analog inputs and secondary internal circuits). No isolation between input signals. |  |

Analog Output Unit
CPM1A-DA041

| CPM1A-DA041 |  |  |  |
| :--- | :--- | :--- | :---: |
| Item |  | CPM1A-DA041 |  |
|  | Input voltage |  |  |

## Analog I/O Units

| Item |  |  | CPM1A-MAD01 |  | CPM1A-MAD11 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Voltage I/O | Current // | Voltage //0 | Current //0 |
| $\begin{aligned} & \text { 亳 } \\ & \frac{\square}{4} \end{aligned}$ | Number of inputs |  | 2 inputs |  | 2 inputs |  |
|  | Input signal range |  | 0 to $10 \mathrm{~V}, 1$ to 5 V | 4 to 20 mA | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V}, 0$ to 10 V , or - 10 to 10 V | 0 to $20 \mathrm{~mA}, 4$ to 20 mA |
|  | Max. rated input |  | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |
|  | External input impedance |  | $1 \mathrm{M} \Omega$ min. | $250 \Omega$ rated | $1 \mathrm{M} \Omega$ min. | $250 \Omega$ |
|  | Resolution |  | 1/256 |  | 1/6000 (full scale) |  |
|  | ${ }^{\text {Overall }}$ | $25^{\circ} \mathrm{C}$ | 1.0\% of full scale |  | $\pm 0.3 \%$ of full scale | $\pm 0.4 \%$ of full scale |
|  |  | 0 to $55^{\circ} \mathrm{C}$ |  |  | $\pm 0.6 \%$ of full scale | $\pm 0.8 \%$ of full scale |
|  | A/D conversion data |  | 8-bit binary |  | Binary data (hexadecimal, 4 digits) <br> -10 to 10 V: F448 to 0BB8 hex <br> Full scale for other ranges: 0000 to 1770 hex |  |
|  | Averaging |  | - |  | Supported (Set for each input using a DIP switch.) |  |
|  | Disconnection detection |  | - |  | Supported |  |
|  | Number of outputs |  | 1 output |  | 1 output |  |
|  | Output signal range |  | 0 to $10 \mathrm{~V},-10$ to 10 V | 4 to 20 mA | 1 to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to 10 V | 0 to $20 \mathrm{~mA}, 4$ to 20 mA |
|  | External output max. current |  | 5 mA | - | - | - |
|  | Allowable external output load resistance |  | - | $350 \Omega$ | $1 \mathrm{k} \Omega \mathrm{min}$. | $600 \Omega$ max. |
|  | External output impedance |  | - |  | $0.5 \Omega$ max. | - |
|  | Resolution |  | $1 / 256(1 / 512$ for output signal range - 10 to 10 V ) |  | 1/6,000 (full scale) |  |
|  | Overall | $25^{\circ} \mathrm{C}$ | 1.0\% of full scale |  | $\pm 0.4 \%$ of full scale |  |
|  | accuracy | 0 to $55^{\circ} \mathrm{C}$ |  |  | $\pm 0.8 \%$ of full scale |  |
|  | Data setting |  | 8 -bit binary with sign bit |  | - |  |
|  | D/A set data |  | - |  | Binary data (hexadecimal, 4 digits) <br> -10 to 10 V: F448 to 0BB8 hex <br> Full scale for other ranges: 0000 to 1770 hex |  |
| Conversion time |  |  | $10 \mathrm{~ms} / \mathrm{Unit}$ max. (See note 2.) |  | $2 \mathrm{~ms} / \mathrm{point}$ ( $6 \mathrm{~ms} \mathrm{for} \mathrm{all} \mathrm{points)}$ |  |
| Isolation method |  |  | Photocoupler isolation between I/O terminals and PLC signals (There is no isolation between the analog I/O signals.) |  | Photocoupler isolation between analog I/O and internal circuits (There is no isolation between the analog I/O signals.) |  |

[^0]

■ CPM1A-TS001/TS002/TS101/TS102

By mounting a Temperature Sensor Unit to the PLC, inputs can be obtained from thermocouples
or platinum resistance thermometers, and temperature measurements can be converted to
binary data (4-digit hexadecimal) and stored in the input area of the CPU Unit

| ltem | CPM1A-TS001/002 | CPM1A-TS101/102 |
| :---: | :---: | :---: |
| Number of inputs | 2 (TS001), 4 (TS002) | 2 (TS101), 4 (TS102) |
| Input types | K, J switchable (Note: Same for all inputs.) | Pt100, JPt100 switchable (Note: Same for all inputs.) |
| Indication accuracy | TThe larger of the indicated value $\pm 0.5 \%$ and $\pm 2^{\circ} \mathrm{C}$ ( See note.) $) \pm 1$ digit max. | [The larger of the indicated value $\pm 0.5 \%$ and $\left.\pm 1^{1} \mathrm{C}\right] \pm 1$ digit max. |
| Conversion time | $250 \mathrm{~ms} / 2$ points (TS001, TS 101); $250 \mathrm{~ms} / 4$ points (TS002, TS 102 ) |  |
| Converted temperature data | Binary (4-digit hexadecimal) |  |
| Isolation method | Photocoupler isolation between the temperature input signals. |  |

Note: The indication accuracy when using a K -type thermocouple for temperatures less than - $100^{\circ} \mathrm{C}$ is $\pm 4^{\circ} \mathrm{C} \pm 1$ digit max.

- Input Temperature Ranges for CPM1A-TS001/002
(The rotary switch can be used to make the following range and
input type settings.)

| Input type | Range $\left({ }^{\circ} \mathrm{C}\right)$ | Range $\left({ }^{\circ} \mathrm{F}\right)$ |
| :---: | :---: | :---: |
| K | -200 to 1300 | -300 to 2300 |
|  | 0.0 to 500.0 | 0.0 to 900.0 |
| J | -100 to 850 | -100 to 1500 |
|  | 0.0 to 400.0 | 0.0 to 750.0 |

- Input Temperature Ranges for CPM1A-TS101/102

| input type settings.) <br> Input type |  |  |
| :--- | :---: | :---: |
| Range $\left({ }^{\circ}\right.$ C) | Range ( ${ }^{\circ}$ F) |  |
| Pt100 | -200 to 650.0 | -300 to $1,200.0$ |
| JPt100 | -200.0 to 650 | -300 to $1,200.0$ |

## - CPM1A-SRT21

CompoBus/S I/O Link Unit
The CompoBus/S I/O Link Unit functions as a slave for a CompoBus/S Master Unit (or an SRM1 CompoBus/S Master Control Unit) to form an /O Link with 8 inputs and 8 outputs between the CompoBus/S I/O Link Unit and the Master Unit.


- Specifications

| Item | CompoBus/S Slave |
| :---: | :---: |
| Master/Slave | CompoBus/S Slave |
| Number of //O bits | 8 input bits, 8 output bits |
| Number of words occupied in CPM2A I/O memory | 1 input word, 1 output word (Allocated in the same way as for other Expansion Units) |
| Node number setting | Set using the DIP switch (before the CPU Unit is turned ON). |

## - CPM1A-DRT21

DeviceNet I/O Link Unit
By connecting a CPM1A-DRT21 DeviceNet I/O Link Unit, a CPM2A can function as a slave for a DeviceNet Master Unit to establish I/O links for


## Dimensions

## CP1H CPU Units

CP1H CPU Units (X/XA/Y Type)


CPM1A-8E $\square \square$
CPM1A-SRT21/CPM1A-DRT21 CPM1A-MADO1 CPMIA-MADO


CPM1A-40ED $\square$


CJ-series Special I/O Units and CPU Bus Units


## Instructions


$\square$ Sequence Output Instructions


Sequence Output Instruction

\section*{} | CONDITONAL JUMP | CJJN | 511 |
| :--- | :--- | :--- | MULTPLE JUMP JMPO MULTPLE UUMPENO JMEO FOR-NEXT LOOPS FO |  |  | 512 |
| :--- | :--- | :--- |
| BREAKLOOP | BREAK | 514 |
|  |  |  |


$\square$ Sequence Output Instructions

## 



■ Data Movement Instructions

- Increment/Decrement Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| cocie |  |  |



## 

| Instruction | Mnemonic | ${ }_{\text {Function }}^{\text {Funde }}$ |
| :---: | :---: | :---: |
| move | mov | ${ }^{021}$ |
| double move | MovL | 498 |
| Move not | mvN | ${ }^{022}$ |
| doubile move not | MvNL | 499 |
| move bit | моvв | ${ }^{082}$ |
| Move ilit | movo | ${ }^{083}$ |
| MULTIPLE BIT <br> TRANSFE | хепв | 062 |
| block transfer | Xfer | 070 |
| block SET | ${ }_{\text {BSET }}$ | 071 |
| data exchange | хснб | ${ }^{073}$ |
| DOUBLE DATA <br> EXCHANG | xcct | 562 |
| SINGEE WORD DISTREUUE | Dist | ${ }^{080}$ |
| data collect | coul | ${ }^{081}$ |
| MOVE To Register | Move | 560 |
|  | movaw | 561 |


| Instruction | Mnemonic | Funcion |
| :---: | :---: | :---: |
| INCREMENT BINARY | ++ | 590 |
| DOUBLE INCREMENT | ++ | 591 |
| decrement tinaty | -- | 592 |
| DOUBLE DECREMENT BINARY | --L | ${ }_{593}$ |
| Increment bci | + + B | 594 |
| DOUBLE INCREMENT <br> BCD | ++BL | ${ }_{595}$ |
| decrement tci | --в | ${ }_{596}$ |
| Double <br> NT BCD | -- ${ }^{\text {LL }}$ | 597 |

## $\square$ Symbol Math Instruction

| Instruction | Mnemonic | Function |
| :---: | :---: | :---: |
| SIGNED BINARY ADD | + | 400 |
| DOUBLE SIGNED BINARY ADD WITHOUT CARR | + | 401 |



 | BCD AD |
| :---: |
| COARY |
| Dovib |
| witheur |

| DOUBLE SIGNED BINARY ADD WITH CARRY | +ct | ${ }^{403}$ |
| :---: | :---: | :---: |
| BCD ADD WITHOUT <br> CARRY | + ${ }^{\text {+ }}$ |  |
| DOUBLE BCD ADD WITHOUT CARRY | +bl |  |


| DOUBLE BCD ADD <br> UT CARRY | + BL | ${ }^{405}$ |
| :---: | :---: | :---: |
| BCC ADD WTH Catry | + ${ }^{\text {c }}$ | 406 |
|  |  |  |



sicned bic
sabract
CARY

| Double sined |
| :--- |
| BiNAR WTHTCA |


| DOUBLE SIGNED BINARY WITH CARRY | -ct | ${ }_{413}$ |
| :---: | :---: | :---: |
| BCD SUBTRACT WITHOUT CARRY | -8 |  |



$\frac{\text { WTH CAR }}{}$



| Double USIIGN |
| :--- |
| BiNAR MULTIPL |



|  | $* B$ | 424 |
| :--- | :--- | :--- |
| DOUBLE ECCD MUTTPIY | $*$ BL | ${ }^{225}$ |


UnsIGNEE BMar oviof
Double usige
BINAR OVIVIE

| BCD DIVIDE | /B | 434 |
| :--- | :--- | :--- |
| DOUBLE ECD DVIIE | /BL | 435 |


| - Data Conversion Instructions |  |  | Floating-point MathInstructions |  |  | Double-precision Floating-pointInstructions |  |  | $\square$ Subroutine Instructions |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Instruction | Mnemonic | tion |  |  |  | Instuction | Mnem | ${ }_{\text {lunction }}^{\substack{\text { code }}}$ |
| BCD-To-BINARY | ${ }_{\text {Bin }}$ | ${ }_{0}$ | Instruction | Mnemonic | ${ }_{\text {cone }}^{\substack{\text { Funcion } \\ \text { code }}}$ |  |  |  | Instuction | Mnemonic | cincole | Subroutine call | sbs | ${ }_{091}$ |
| DOUBLE BCD-TO-DOUBLE BINARY | BIL | 058 | FLOATNG TO 16-Bit | FIX | 450 | $\begin{aligned} & \text { Pouble fadans } \\ & \text { TO OEREES } \end{aligned}$ | DEGD | ${ }^{850}$ | SUBROUTINE ENTRY | SBN | 092 |
|  |  |  | FLOATING To 32-Bit | FXXL | ${ }_{4}^{451}$ |  |  |  |  | Ret | ${ }^{093}$ |
| BINAFY-To-Bco | вcD | ${ }^{024}$ | 16-bit to floating | FLT | ${ }_{4} 52$ | Double cosine | SIND | ${ }^{851}$ | SUBROUTINE RETURN | мсво | 099 |
| DOUBLE BINARY-TO-DOUBLE BCD | BCDL | 059 | 32-BIT TO FLOATING | \&TL | ${ }_{453}$ |  | Cosd | ${ }_{853}$ |  | GSEN | ${ }_{751}$ |
|  |  |  |  | + | 454 | double tangent T | tand |  |  |  |  |
| 2 2' Complement | NEG | 160 | FLOATING-POINT SUBTRAC | - | ${ }_{455}$ | Double Arc Sine | AsIND | ${ }^{854}$ | GLOBAL SUBROUTINE ENTRY | GRET | ${ }^{75}$ |
| DOUBLE $2^{\prime} \mathrm{S}$ COMPLEMENT | NEGL | 161 | flooting Point <br> Mutirle |  | ${ }_{456}$ |  | atand | ${ }^{855}$ | GLOBAL <br> SUBROUTINE RETURN | Gsss | 750 |
| Doublers | SIGN | 600 |  | * ${ }^{\text {F }}$ |  |  |  | ${ }^{856}$ |  |  |  |
| data decooer | MLPX | 076 | FLOATING- POINT | F | ${ }^{457}$ | DOUBLE SQUARE ROOT | Sorto | ${ }^{857}$ | $\square$ Interrupt Control Instructions |  |  |
| data encooler | dMPX | 077 | ${ }^{\text {degres }}$ (obiole | ${ }_{\text {RAD }}$ | ${ }_{458}$ | DoUBLEEXPONENT | EXPD | ${ }^{858}$ | Instuction | Mnemonic | cod |
| AsCli convert | Asc | 086 | ${ }_{\substack{\text { Radians } \\ \text { Dockes }}}^{\text {a }}$ | DEG | 459 |  | -060 | ${ }^{859}$ | SEt MTEREVUPT MASK | Msks | ${ }_{690} 69$ |
| ASCII TO HEX | HEX | 162 |  |  |  | DOUBLE LOGARITHM |  |  |  |  |  |
| COLUMN TO LINE | LINE | ${ }^{063}$ | Cosine | cos | 460 | DOUBLE EXPO- <br> NENTIAL POWER | Pwbo | ${ }^{860}$ | Clear INTERUPT | $\mathrm{cu}^{\text {L }}$ | 691 |
| Line to column | colm | ${ }_{0} 64$ |  |  | ${ }_{461}$ |  |  |  |  | -1 | 693694 |
| SIGNED BCD-TO- | Bins | 40 | tangent | tan | ${ }_{462}^{461}$ | (evile symbol |  |  | ENabil interuyts |  |  |
| Double sind | BISL | ${ }^{472}$ | $\begin{aligned} & \hline \text { ARC SINE } \\ & \hline \text { ARC COSINE } \end{aligned}$ | Asin | $\begin{aligned} & 463 \\ & \hline 464 \\ & \hline 4 \end{aligned}$ |  |  |  | $\square$ High-speed Counter and Pulse Output Instructions |  |  |
|  | BISL | 472 |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \text { SIGNED BINARYTO- } \\ & \text { BCD } \end{aligned}$ | 8cos | ${ }^{471}$ | $\begin{aligned} & \text { ARC TANGENT } \\ & \hline \text { SQuaRE Root } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { ATAN } \\ & \text { Sort } \\ & \hline \end{aligned}$ | $\begin{aligned} & 465 \\ & \hline 466 \\ & \hline 46 \end{aligned}$ | Table Data Processing Instructions |  |  | Instruction | Mnemonic |  |
|  | BSSL | ${ }^{473}$ | Floating-point Math Instructions |  |  |  |  |  | MODE CONTROL | "N1 | ${ }^{880}$ |
|  |  |  |  |  |  |  | PRV | ${ }_{881}$ |  |  |  |  |  |
|  | GRY | ${ }^{474}$ |  |  |  | Instruction |  |  | Mnemonic | Functor |  |
|  |  |  | Instruction | Mnemonic | cin |  | Stack | SSET | ${ }^{630}$ |  | PRV2 | ${ }^{88}$ |
| $\square$ Special Math Instructions |  |  | EXPONENT | $\frac{\text { ExP }}{\text { Lo6 }}$ | $\begin{aligned} & 467 \\ & \hline 468 \\ & \hline 68 \end{aligned}$ | $\begin{aligned} & \text { PUSH ONTO STACK } \\ & \hline \text { FRRST IN FIRST OUT } \\ & \hline \end{aligned}$ | $\begin{array}{\|l\|l} \text { pusH } \\ \hline \text { FFFO } \end{array}$ | ${ }^{632}$ | COMPARISON TABLE LOAD | ствь | ${ }^{882}$ |
| Instruction | Mnemonic | Finction | LOGARITHM |  |  |  |  | ${ }^{633}$ |  |  |  |
| BINAYY Root | вотв |  | $\begin{aligned} & \text { Exponential } \\ & \text { Power } \\ & \hline \text { Pow } \end{aligned}$ | PWr | ${ }_{840}$ |  | LFO | ${ }^{634}$ | speed oute | sped | ${ }^{885}$ |
| bCo sauare root | Rоот | 072 |  | $\quad+$$=F_{1}<>F_{1}$,$<F_{1}<=F$, |  |  |  | ${ }^{631}$ | SET PULSES PULSE OUTPUT | Sts | ${ }^{886}$ |
| ARTHMEICIC Process | APR | 069 | $\underbrace{\substack{\text { a }}}_{\substack{\text { Floating Symbol } \\ \text { Comparson }}}$ |  |  | SEt recorol location | Stre | ${ }^{635}$ |  |  | ${ }^{887}$ |
| FLOATING POINT <br> DIVID | oiv |  |  |  |  | ECoro numb | GET | ${ }_{636}$ | ACCELERATION CONTROL | acc | ${ }^{888}$ |
| bit counter | вCNT | 067 |  |  |  | DATA SEARCH | sfch | 181 | ORIGIN SEACH | org | ${ }^{889}$ |
|  |  |  | FLOATING- POINT TO ASCI | FSTR | ${ }^{448}$ | SWAP BYTES <br> FIND MAXIMUM | SWAP | ${ }^{637}$ | $\begin{aligned} & \text { ULSE WTH V VaRABLIE } \\ & \text { UUTF FACTOA } \end{aligned}$ | pwn | ${ }^{89} 1$ |
| Logic Instructions |  |  |  |  |  |  | max | 182 |  |  |  |
| Instruction | Mnemonic | coinction | $\stackrel{\text { floating Point }}{ }$ | fval | ${ }^{449}$ | FIND MNIM | Min | ${ }^{183}$ | $\square$ Step Instruc | tions |  |
| Locical and | anow | ${ }^{034}$ |  |  |  | SUM | sum | 184 <br> 180 | Instuction | Mnemonic | anction |
| double logical ano | ANOL | 610 | Floating-poi | int Instru | uctions | stack siz read | ssum | ${ }^{638}$ | $\xrightarrow[\text { STEP DEENE }]{ }$ | STEP | 008 |
| Logical or | orw | 035 | Instruction | Mnemoric | Function | Stack data mead | sread | 639 | STEP STAAT | SNXT | 009 |
| doubil Logical or | ormL | 611 |  |  |  |  |  |  |  |  |  |
| ExClusive or | Xorw | ${ }_{0} 036$ | Double foating | FxD | ${ }^{841}$ | STACK data OUERWRITE | swRit | ${ }^{640}$ | $\square$ Basic I/O Un | it Instru | ctions |
| ${ }_{\text {Dob }}^{\text {Double EXCLUSIVE }}$ | xorl | ${ }^{612}$ | (e) | fxLD | ${ }_{842}$ | Stack data insert | sins | ${ }_{641}$ | Instuction | Mnemonic | (enction |
| ExClusive nor | XNRW | 037 |  |  |  | ETE | SDEL | ${ }_{642}$ | IO REFRESH | IORF | ${ }^{097}$ |
| Double ExClusive | XNRL | ${ }^{613}$ |  | DBL | ${ }^{843}$ | $\square$ Data Control | ol Instruc | ctions | 7-SEMENT DECODER | SoEc | 078 |
|  |  |  |  |  |  |  |  |  | Digral swich invut | DSw | 210 |
| COMPLement | com | 029 | doublefloating | ОвL | ${ }^{844}$ | Instuction | Mnemonic | Fonction | tenkey input | TkY | 211 |
| Double complement | comL | 614 |  |  | ${ }^{845}$ | PII CONTROL | PID | 190 | HEXADECIMAL KEY INPUT | Hку | 212 |
|  |  |  |  |  |  |  | ${ }^{\text {PIDAT }}$ | 191 | Matrix InPut | мтR | 213 |
|  |  |  | FLOATINGPOIN <br> SUBTRAC | - | ${ }^{846}$ | LIMIT Control | Lnt | ${ }^{680}$ | 7-SEEMENT DISPLAY | ${ }^{\text {7SEG }}$ | 214 |
|  |  |  |  |  |  | Dead bano control | Bano | ${ }^{681}$ |  |  |  |
|  |  |  | MULTIPLY | * | ${ }^{847}$ | DeAA ZONE CONTrol | ZONE | ${ }^{682}$ | $\begin{aligned} & \substack{\text { REEALILGENT IO }} \\ & \hline \text { REA } \end{aligned}$ | ${ }^{10 R D}$ | 222 |
|  |  |  | $\begin{aligned} & \text { DoUBLE } \\ & \text { FLOATIIGGOINT } \\ & \text { DIVIE } \\ & \hline \end{aligned}$ | 10 | ${ }^{848}$ | TMMEPPOPORTIONAL | ${ }^{\text {TpO }}$ | ${ }^{685}$ | INTELIGENT IO WRITE | Iown | ${ }^{223}$ |
|  |  |  | DOUBLE DEGREES TO RADIANS | RADD | ${ }^{849}$ | SCALING | scl | 194 <br> 486 |  | DLINK | ${ }^{226}$ |
|  |  |  |  |  |  | SCALING 3 | scl3 | ${ }^{487}$ |  |  |  |
|  |  |  |  |  |  | age | avg | 195 |  |  |  |


| Serial Communications Instructions |  |  |
| :---: | :---: | :---: |
| Instruction | Mnemonic | Function |
| PROTOCOL MACRO | PMCR | 260 |
| transmit | T×0 | ${ }^{236}$ |
| recelve | R×0 | 235 |
| TRANSMIT VIA SERIAL UNIT UNI | Txou | 256 |
| RECEIVE VIA SERIAL COMM | Rxou | 255 |
| CHANGE SERIAL PORT SETUP | stup | 237 |


| Instruction | Mnemonic | Funcid |
| :---: | :---: | :---: |
| NetWork Send | send | 090 |
| NETWORK RECEVE | RECV | 098 |
| delver command | Cmno | 490 |
| EXPLLCIT MESSAGE <br> SEND | ExPlt | 720 |
| EXPLICIT GET <br> ATTRIBUTE | Egatr | ${ }^{21}$ |
| EXPLICIT SET ATTRIBUTE | Esatr | ${ }^{722}$ |
| EXPLCIT WORD READ | ECHRD | ${ }^{223}$ |
| EXPLCTT WORD Wate | Echwr | 124 |

Display Instructions


| DISPLAY MESSAGE | ms6 | 046 |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { DISPAPAY-SEGMENT } \\ & \text { DATA } \end{aligned}$ | sch | ${ }_{0} 04$ |
| $\underset{\substack{\text { CONTROL } \\ 7 \text { TSEGMENT }}}{ }$ | Sctrl |  |

Clock Instructions

$\square$ Debugging Instructions

| Instruction | Mnemonic | ${ }_{\text {Function }}^{\text {coide }}$ |
| :---: | :---: | :---: |
| TRACE MEMORY <br> SAMPLIN | trsm | 045 |


\section*{$\square$ Failure Diagnosis Instructions} | Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| cocid |  |  |

 $\substack{\text { FAlluge pont } \\ \text { CEETETION }}$

- Other Instructions

| Instruction | Mnemonic | Function |
| :---: | :---: | :---: |
| SEt Cabry | sтc | ${ }^{040}$ |
| Clear carry | cıC | 041 |
| EXTEND MAXIMUM CYCLE TIME | wot | 094 |
| SAVE CONDITION FLAGS | ccs | 282 |
| LOAD CONDITION FLAGS | cct | 283 |
| CONVERT ADDRESS FROM CS | fram | 284 |
| conver adises | tocv | 285 |

## Block Program Instructions

| Instructions |  |  |
| :--- | :--- | :--- |
| Instruction | Mnemoric | Funcion |
| cooden |  |  |


| Sruction | Mnemonic | ${ }_{\text {Funcio }}$ code |
| :---: | :---: | :---: |
| BLOCK PROGRAM BEGIN | BPRG | ${ }^{096}$ |
|  | Bend | ${ }^{801}$ |
| Block progatam PAUSE | BPPS | ${ }^{811}$ |
| BLOCK PROGRAM RESTAR | BPRS | ${ }^{812}$ |
| CONDITIONA | ccs | 282 |

Task Control Instructions

| Instruction | Mnemonic | come |
| :---: | :---: | :---: |
| TASK on | тком | 820 |
| TASK off | ткоғ | 821 |

$\square$ Model Conversion
Instructions

| Instructio | Mnemonic | Funcie |
| :---: | :---: | :---: |
| Blocktran | Xerrac | 565 |
| SINGLE WORD | ${ }_{\text {distc }}$ | ${ }_{566}$ |
| data collect | couc | 567 |
| move bit | movic | 568 |

$\square$ Special Instructions fo
Speciaion Blocks
Function

| Instruction | Mnemonic | ${ }_{\text {Function }}^{\text {coide }}$ |
| :---: | :---: | :---: |
| GEt Variable id | GETID | 286 |

## Ordering Information

## $\square$ CPU Units

| CPU Unit | Specifications |  |  |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Power supply | Output method | Inputs | Outputs |  |  |
| CP1H-X CPU Units <br> Memory capacity: 20 Ksteps <br> High-speed counters: 100 kHz, 4 axes <br> Pulse outputs: $100 \mathrm{kHz}, 2$ axes <br> 30 kHz, 2 axes | AC power supply | Relay output | 24 | 16 | CP1H-X40DR-A | CE, N |
|  | $\underset{\text { supply }}{\text { DC power }}$ | Transistor output (sinking) |  |  | CPIH-X40DT-D | CE, N |
|  |  | Transistor output (sourcing) |  |  | CP1H-X40DT1-D | CE, N |
| CP1H-XA CPU Units <br> Memory capacity: 20 Ksteps <br> High-speed counters: 100 kHz, 4 axes <br> Pulse outputs: $100 \mathrm{~Hz}, 2$ axes <br> $30 \mathrm{kHz}, 2$ axes <br> Analog inputs: 4 <br> Analog outputs: 2 | AC power supply | Relay output | 24 | 16 | H-XA400R-A | CE, N |
|  | DC powersupply | Transistor output (sinking |  |  | CP1H-XA40DT-D | CE, N |
|  |  | $\underset{\substack{\text { Transistor output } \\ \text { (sourcing) }}}{ }$ |  |  | CP1H-XA400T1-D | CE, N |
| CP1H-Y CPU Units <br> Memory capacity: 20 Ksteps <br> High-speed counters: $1 \mathrm{MHz}, 2$ axes $100 \mathrm{~Hz}, 2$ axes <br> Pulse outputs: 1 MHz , 2 axes <br> $30 \mathrm{kHz}, 2$ axes | $\underset{\text { scopply }}{\text { DC power }}$ | Transistor output (sinking) | $\begin{gathered} 12 \\ \begin{array}{c} 12 \\ \text { line-driver input, } \\ 2 \text { axes } \end{array} \\ \hline \end{gathered}$ | $\begin{gathered} 8 \\ \begin{array}{c} \text { line-driver input, } \\ \text { liaxes } \end{array} \end{gathered}$ | CP1H-Y200T-D (To be released soon.) | - |


| Name | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: |
| RS-232C Option Board | For CPU Unit option port. | CP1W-CIFO1 | CE, N |
| RS-422A/485 Option Board | For CPU Unit option port. | CP1W-CIF11 | CE, N |
| Memory Cassette | Can be used for backing up programs or auto-booting. | CP1W-ME05M | CE, N |

## Expansion Units

| Name | Output method | Inputs | Outputs | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Expansion //O Units | Relay | 24 | 16 | CPM1A-40EDR | $\mathrm{CE}, \mathrm{N}$ |
|  | Transistor (sinking) |  |  | CPM1A-40EDT | CE, N |
|  | Transistor output (sourcing) |  |  | CPM1A-40EDT1 | CE, N |
|  | Relay | 12 | 8 | CPM1A-20EDR1 | U, C, CE |
|  | Transistor (sinking) |  |  | CPM1A-20EDT | U, C, $\mathrm{N}, \mathrm{CE}$ |
|  | Transistor output (sourcing) |  |  | CPM1A-20EDT1 | U, C, N, CE |
|  | - | 8 | - | CPM1A-8ED | U, C, N, CE |
|  | Relay | - | 8 | CPM1A-8ER | U, C, N, CE |
|  | Transistor (sinking) | - | 8 | CPM1A-8ET | U, C, N, CE |
|  | Transistor output (sourcing) |  |  | CPM1A-8ET1 | U, C, N, CE |
| Analog Input Unit | Analog (resolution: $1 / 6000$ ) | 4 | - | CPM1A-AD041 | U, C, N, CE |
| Analog Output Unit | Analog (resolution: 1/6000) | - | 4 | CPM1A-DA041 | UC1, CE |
| Analog I/O Units | Analog (resolution: 1/256) | 2 | 1 | CPM1A-MAD01 | UC1, CE |
|  | Analog (resolution: 1/6000) | 2 | 1 | (1) CPM1A-MAD11 | U, C, N, CE |
| DeviceNet //O Link Unit | - | $\begin{aligned} & 32 \\ & \text { (/O link input bits) } \end{aligned}$ | (I/O link input bits) | CPM1A-DRT21 | U, C, CE |
| CompoBus/S IO Link <br> Unit | - | $\stackrel{8}{\text { (I/O link input bits) }}$ | (I/O link input bits) | CPM1A-SRT21 | U, C, N, CE |
| Temperature Sensor Units | 2 thermocouple inputs |  |  | CPM1A-TS001 | U, C, N, CE |
|  | 4 thermocouple inputs |  |  | CPM1A-TS002 | U, C, N, CE |
|  | 2 platinum resistance thermometer inputs |  |  | CPM1A-TS 101 | U, C, N, CE |
|  | 4 platinum resistance thermometer inputs |  |  | ( CPM1A-TS 102 | U, C, N, CE |

## I/O Connecting Cable

| Name | Specifications | Model | Standards |
| :--- | :--- | :--- | :--- |
| I/O Connecting Cable | 80 cm (for CPM1A Expansion Units) | CP1W-CN811 | CE,N |

Note: An IO Connecting Cable (approx. 6 cm ) for horizontal connection is provided with CPMIA Expansion Units

## Programming Devices

| Name | Specifications |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: |
| CX-One <br> FA Integrated Tool Package | CX-One is a package that integrates the Support Software for OMRON PLCs and components. CX-One runs on the following OS S: Windows 98SE, Me, NT 4.0 (Service Pack 6a), 2000 (Service Pack 3 or higher), or XP <br> CX-One Includes CX-Programmer Ver 6. $\square$ and CX-Simulator Ver.1. $\square$ For details, refer to the CX-One catalog (Cat. No. R134). | One license | CXONE-ALOTC-E | - |
|  |  | Three licenses | CXONE-ALOOC-E |  |
|  |  | Ten licenses | CXONE-ALIOC-E |  |
|  | CX-Programmer and CX -Simulato can still be ordered individually in the following model number. |  |  |  |
| CX-ProgrammerVer. $6 . \square$ | Support Software for Windows <br> OS: Windows 98SE, Me, NT 4.0 (Service Pack 6a), 2000 (Service Pack 3 or higher), or XP | One license | WS02-CXPC1-E-V6■ |  |
|  |  | Three licenses | WS02-CXPC1-E03-V6ם |  |
|  |  | Ten licenses | WS02-CXPC1-E10-V6ם |  |
| CX-Simulator Ver. $1 . \square$ | Support Software for Windows <br> OS: Windows 98SE, Me, NT 4.0 (Service Pack 6a), 2000 (Service Pack 3 or higher), or XP | One license | Ws02-SIIC 1 -E | - |
| Programming Device Connecting Cable for CP1W-CIF01 RS-232C Option Board(See note.)$\qquad$ | Connects DOS computers, D-Sub 9-pin (Length: 2.0 m ) | For anti-static connectors | xW2Z-200s-CV | - |
|  | Connects DOS computers, D-Sub 9-pin (Length: 5.0 m ) |  | XW2Z-500s-CV |  |
|  | Connects DOS computers, D-Sub 9-pin (Length: 2.0 m ) |  | xw2z-200s-V |  |
|  | Connects DOS computers, D-Sub 9-pin (Length: 5.0 m ) |  | xw2z-500s-v |  |
| USB-Serial Conversion Cable (See note.) | USB-RS-232C Conversion Cable (Length: 0.5 m ) and PC driver (on a CD-ROM disc) are included. Complies with USB Specification 1.1 <br> On personal computer side: USB (A plug connector, male) <br> On PLC side: RS-232C (D-sub 9-pin, male) <br> Driver: Supported by Windows $98, \mathrm{Me}, 2000$, and XP |  | CSIW-CIF31 | - |

Note: Cannot be used with a peripheral USB porte. To connect to a personal computer via a peripheral USB port, use commercially-avilable USB cable (A or B type, male).

- Optional Products, Maintenance Products and DIN Track Accessories

| Name | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: |
| Battery Set | For CP1H CPU Units <br> (Use batteries within two years of manufacture.) | CJIW-bato | CE |
| DIN Track | Length: $0.5 \mathrm{~m} ;$ Height: 7.3 mm | PFP-50N | - |
|  | Length: 1 m ; Height: 7.3 mm | PFP-100N |  |
|  | Length: 1 m ; Height: 16 mm | PFP-100N2 |  |
| End Plate | There are 2 stoppers provided with CPU Units and I/O Interface Units as standard accessories to secure the Units on the DIN Track. | PFP-M |  |

## Ordering Information

| Category | Name | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: | :---: |
| CP1H CPU Unit options | CJ Unit Adapter | Adapter for connecting CJ-series Special I/O Units and CPU Bus Units (includes CJ-series End Cover) | CP1W-EXT01 | UC1, <br> CE, N, L |
| CJ-series Special I/Q Units | Analog Input Units | 8 inputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: $1 / 8,000$; Conversion speed: $250 \mu$ s/input max. (Can be set to $1 / 4,000$ resolution and 1 ms /input.) | CJ1W-ADO81-V1 |  |
|  |  | 4 inputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to 10 V , -10 to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: $1 / 8,000$; Conversion speed: $250 \mu$ s/input max. (Can be set to $1 / 4,000$ resolution and $1 \mathrm{~ms} /$ input.) | CJIW-ADO41-V1 |  |
|  | Analog Output Units | 8 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to 10 V ) Resolution: 1/4,000; Conversion speed: 1 ms/output max (Can be set to $1 / 8000,250 \mu \mathrm{~s} /$ output) | CJIW-DA08V |  |
|  |  | 8 outputs ( 4 to 20 mA ) <br> Resolution: 1/4,000; Conversion speed: $1 \mathrm{~ms} /$ output max <br> (Can be set to $1 / 8,000,250 \mu \mathrm{~s} /$ output) | CJIW-DA08C | UC1, CE, N |
|  |  | 4 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: $1 / 4,000$, Conversion speed: $1 \mathrm{~ms} /$ point max. | CJIW-DA041 | UC1, CE, N, L |
|  |  | 2 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 1/4,000; Conversion speed: $1 \mathrm{~ms} /$ output max. | CJIW-DA021 |  |
|  | Analog I/O Unit | 4 inputs, 2 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 1/4000; Conversion speed: $1 \mathrm{~ms} /$ point max (Can be set to $1 / 8,000,250 \mu \mathrm{~s} /$ point) | CJ1W-MAD42 |  |
|  | Process Input Units | 4 inputs, B, J, K, L, R, S, T; Conversion speed: $250 \mathrm{~ms} / 4$ inputs | CJIW-PTS51 | UC1, CE |
|  |  | 4 inputs, Pt100 $\Omega$ ( (Js, IEC), JPt100 $\Omega$, Conversion speed: 250 mss 4 inputs | CJIW-PTS52 |  |
|  |  | 2 inputs, B, E, J, K, L, N, R, S, T, U, W, Re5-26, PL $\pm 100 \mathrm{mV}$, Resolution: 1/64,000; Conversion speed: $10 \mathrm{~ms} / 2$ inputs | CJIW-PTS 15 |  |
|  |  | 2 inputs, Pt100, JPt100, Pt50, Ni508.4; <br> Resolution: 1/64,000; Conversion speed: $10 \mathrm{~ms} / 2$ inputs | CJIW-PTS16 |  |
|  |  | 2 inputs, 0 to $1.25 \mathrm{~V},-1.25$ to $1.25 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V},-5$ to $5 \mathrm{~V}, 0$ to 10 V , -10 to $10 \mathrm{~V}, \pm 10-\mathrm{V}$ selectable range, 0 to $20 \mathrm{~mA}, 4$ to 20 mA | CJ1W-PDC 15 |  |
|  | Temperature Control Units | 4 loops, thermocouple input, NPN output | CJ1W-TC001 | UC1, CE, N, L |
|  |  | 4 loops, thermocouple input, PNP output | CJ1W-TC002 |  |
|  |  | 2 loops, thermocouple input, NPN output, heater burnout detection function | CJIW-TC003 |  |
|  |  | 2 loops, thermocouple input, PNP output, heater burnout detection function | CJIW-TC004 |  |
|  |  | 4 loops, platinum resistance thermometer input, NPN output | CJIW-TC101 |  |
|  |  | 4 loops, platinum resistance thermometer input, PNP output | CJ1W-TC102 |  |
|  |  | 22 loops, platinum resistance thermometer input, NPN output, heater burnout detection function | CJIW-TC103 |  |
|  |  | 2 loops, platinum resistance thermometer input, PNP output, heater burnout detection function | CJIW-TC104 |  |
|  | CompoBus/S Master Unit | CompoBus/S remote //0, 256 points max. | CJ1W-SRM21 |  |
| $\begin{aligned} & \text { CJ-series } \\ & \text { CPU Bus } \end{aligned}$Units | Controller Link Units | Wired (Shielded twisted-pair cable) | CJ1W-CLK21-V1 | UC1, <br> CE, N, L |
|  | Serial Communications Units | 1 RS-232C port and 1 RS-422A/485 port | CJIW-SCU41-V1 |  |
|  |  | 2 RS -232C ports | CJIW-SCU21-V1 |  |
|  | Ethernet Unit | 100Base-TX | CJ1W-ETN21 |  |
|  | DeviceNet Unit | Functions as master and/or slave; allows control of 32,000 points max. per master. | CJ1W-DRM21 |  |

> Read and Understand this Catalog
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## DIMENSIONS AND WEIGHTS

Dimen
shown.

## PERFORMANCE DATA

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[^0]:    Note 1 : The voltage output and current output can be used at the same time for analog outputs, but the total output must not exceed 21 mA .2: The conversion time is the total time for 2 analog

